LA-UR-95-- 3 1 4 8

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SUBMITTED TO

International Conference on Turbulent Heat Transfer, San Diego, California, March 10-15, 1996

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FORM NO 836 R4 ST. NO 2629 5/81

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Interim ICASE Report

and

Draft Paper for

the

International Conference on Turbulent Heat Transfer
San Diego, California
March 10-15, 1996

A NON-LINEAR ALGEBRAIC MODEL FOR THE TURBULENT SCALAR FLUXES

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^{*}This research was supported by the National Aeronautics and Space Administration under NASA Contract No. NAS1 - 19480 while the authors were in residence at the Institute for Computer Applications in Science and Engineering (ICASE), NASA Langley Research Center, Hampton, VA 23681-0001.

1 Introduction

The purpose of this paper is to report on a novel approach to the modelling of the turbulent scalar fluxes $(u_i \overline{\theta})$ which arise as a consequence of time averaging the transport equation for a mean scalar (Θ) . The focus of this paper will be on the case where Θ is a 'passive' scalar; the extension of this approach to cases involving buoyancy and compressibility will be briefly discussed.

The need for a new approach to modelling the scalar fluxes stems from the lack of realism in the performance of the simple gradient-transport models and the inadequacy of many of the assumptions underlying the more complicated scalar-flux transport closures. The problems with the simple gradient-transport closures are well known. In models of this type, the scalar fluxes are related to the mean scalar field via a scalar turbulent diffusivity (Γ_t), thus:

$$-\overline{u_i\theta} = \Gamma_t \frac{\partial \Theta}{\partial x_i} \tag{1}$$

where, for example:

$$\Gamma_t = \frac{C_\mu}{\sigma_\mu} \frac{k^2}{\epsilon} \tag{2}$$

k and ϵ are, respectively, the turbulent kinetic energy and dissipation rate while σ_{θ} is the appropriate Prandtl–Schmidt number. Models of this type fail badly in complex and strongly-buoyant flows as Eq. (1) is clearly too simplistic in its representation of the scalar fluxes (note, for example, the absence of an explicit dependence on the Reynolds stresses or on the mean shear). Equation (1) also implies that the turbulent diffusivity is isotropic and that the turbulent scalar fluxes and the mean scalar gradients are aligned. Neither result holds true in complex two- and three-dimensional shear flows. Batchelor (1949) proposed a generalization to the gradient-transport hypothesis involving the definition of a turbulent eddy-diffusivity tensor (D_{ty}), thus:

$$-\overline{u_i\theta} = D_{ij}\frac{\partial\Theta}{\partial x_k} \tag{3}$$

Several attempts have been made at obtaining a practical representation for D_{ij} . Some of these (by Yoshizawa (1985,1988), Rogers et al. (1989) and Rubinstein and Barton (1991)) will be discussed later in the paper. At this point, however, it is convenient to mention two such proposals. Daly and Harlow (1970) made D_{ij} directly proportional to the Reynolds stresses, thus:

$$-\overline{u_t\theta} = constant \times \overline{u_t u_k} \frac{\partial \Theta}{\partial x_k}$$
 (4)

This model has found widespread due to its relative simplicity and ability to account for the anisotropy of turbulent diffusivity. Launder (1988, 1995) has proposed the "WET" model for the scalar fluxes obtains these quantities as:

$$-\overline{u_i\theta} = \frac{k}{\epsilon} (\beta_1 \overline{u_i u_k} \frac{\partial \Theta}{\partial x_k} + \beta_2 \overline{u_k \theta} \frac{\partial U_i}{\partial x_k} + \beta_3 g_i \overline{\theta^2})$$
 (5)

Launder's model is unique amongst the existing algebraic closures in (i) being implicit in the scalar fluxes and (ii) not being of the gradient-transport type in that it clearly allows for finite scalar

fluxes in the absence of mean scalar gradients. This is indeed possible in practice but only due to the action of transport by the mean-flow and turbulence: a non-local effect which cannot be catered for within the context of algebraic closures. Few examples of the use of the "WET" model in complex shear flows exist and hence little further can be said about the validity of such formulation.

The alternative route to the gradient-transport hypothesis involves calculating the scalar fluxes, directly, either from the solution of modelled differential transport equations in which they are the dependent variables or from simplified algebraic relations derived from these differential equations. The exact equations are of the form:

$$\frac{\partial(\overline{u_{1}\theta})}{\partial t} + \frac{\partial(U_{k}\overline{u_{1}\theta})}{\partial x_{k}} = -\overline{u_{k}\theta} \frac{\partial U_{1}}{\partial x_{k}} - \overline{u_{k}u_{1}} \frac{\partial \Theta}{\partial x_{k}} - \beta g_{i}\overline{\theta^{2}}$$

$$- (\gamma + \nu) \frac{\partial \theta}{\partial x_{k}} \frac{\partial u_{1}}{\partial x_{k}}$$

$$- \frac{\partial}{\partial x_{k}} (\overline{u_{k}u_{i}\theta} + \frac{\overline{p'\theta}}{\rho} \delta_{ik} - \gamma \overline{u_{i}} \frac{\partial \theta}{\partial x_{k}} - \nu \overline{\theta} \frac{\partial u_{1}}{\partial x_{k}})$$

$$- \frac{\overline{p'}}{\rho} \frac{\partial \theta}{\partial x_{1}}$$
(6)

where β is the volumetric expansion coefficient , γ is molecular diffusivity, ρ is the fluid density, and p' is the fluctuating pressure.

The first three terms on the right-hand-side of Eq. (6) represent, respectively, the rates at which $\overline{u_i\theta}$ is generated by the turbulent interaction with the mean field and by the body forces (buoyancy in this case). These terms are the only ones in Eq. (6) that can be treated exactly; the remainder must first be approximated before the system of equations can be solved for the scalar fluxes. The viscous destruction term (which is zero only in isotropic turbulence) is usually neglected in non-isotropic turbulence as well by invoking the assumption of local isotropy at high turbulence Reynolds numbers. This assumption does not rationally account for the energy cascade to high wave numbers, a process which suggests that some dissipation needs to be present (the DNS results of Rogers et al. (1989) obtained in a fully-developed turbulent channel flow even suggest that this term acts as a production term in certain circumstances!). The turbulent-transport term is either neglected (as in conventional Algebraic Stress Model closures) or is modelled via a gradienttransport relation. The last term in Eq. (6), the fluctuating pressure-scalar-gradient correlations. may be viewed as the counterpart of the pressure-strain term in the $\overline{u_iu_j}$ transport equation. It is clearly an important agency which requires careful modelling and it is perhaps here that current scalar-flux-transport models are least well developed. An exact expression for this quantity (derived from the instantaneous equations for the scalar and the i-component of momentum) is given as:

$$\frac{\overline{p'\partial\theta}}{\rho\partial x_1} = \frac{1}{4\pi} \int \left(\frac{\partial^2 u'_1 u'_m}{\partial x_l \partial x_m} \frac{\partial \theta}{\partial x_1} + 2 \frac{\partial U'_1}{\partial x_m} \frac{\partial u_{i_0}}{\partial x_l} \frac{\partial \theta}{\partial x_1} + \frac{\beta g_1}{\Theta'} \frac{\overline{\partial \theta}}{\partial x_l} \frac{\partial \theta}{\partial x_l} \right) \frac{dVol}{\mathbf{r}}$$
(7)

where the primed quantities are evaluated at distance $\mathbf{x} + \mathbf{r}$.

There are three distinct groupings of terms in Eq. (7): one which is associated with purely turbulence interactions (the 'slow' part, $\pi_{ij,1}$), another which involves interactions between the mean

velocity gradients and fluctuating quantities (the 'rapid' part, $\pi_{ij,2}$) and a third which involves the body forces ($\pi_{ij,3}$). Note that the gradients of the mean scalar do not appear explicitly in Eq. (7).

The conventional approach to modelling the integral expression in Eq. (7) has been to model each of its components separately. Thus, Monin (1965), by analogy with Rotta's return-to-isotropy proposal, suggests the model:

$$\pi_{ij,1} = -C_{1\theta} \frac{\epsilon}{k} \overline{u_i \theta} \tag{8}$$

Launder (1975) models the 'rapid' part as:

$$\pi_{11,2} = -C_{2\theta}P_{i\theta,1} \tag{9}$$

where $P_{i\theta,1} \equiv -\overline{u_k \theta} \frac{\partial U_i}{\partial x_k}$

This, by simple extension to buoyant flows, gives:

$$\pi_{ij,3} = -C_{3\theta}G_{i\theta} \tag{10}$$

where $G_{i\theta} \equiv -\beta g_i \overline{\theta^2}$.

This piece-wise approach to modelling the integral expression (inspired by the once fashionable practice of modelling the equivalent terms in the $\overline{u_t u_j}$ equations, since abandoned; e.g. Speziale et al. 1991) results in the absence from the model of any explicit dependence on terms containing $\overline{u_i u_j}$ and $\frac{\partial \Theta}{\partial x_k}$. This is a serious omission as the role of the fluctuating pressure-scalar-gradient correlations is to counter-balance the rate of production of $\overline{u_i \theta}$, including that due to the interaction of the Reynolds stresses with the scalar gradients. Interestingly enough, in a DNS study of passive scalar dynamics for fully-developed turbulent channel flow, Rogers et al. (1989) remark that "the results indicate that splitting the pressure term into rapid and slow parts is not a good idea". Jones and Musonge (1987) appear to have been among the first to attempt to restore such dependence. They argued that $\pi_{ij,1}$ and $\pi_{ij,2}$ should be modelled together since both ultimately depend on the mean field. Their proposal reads:

$$\pi_{ij,1} + \pi_{ij,2} = -C_{1\theta} \frac{\overline{u_i \theta}}{\tau} + C_{2\theta} a_{ij} \frac{\partial \Theta}{\partial x_j} + d_{ijk} \frac{\partial U_j}{\partial x_k}$$
 (11)

where

$$a_{ij} = (\frac{\overline{u_i u_j}}{q^2} - \frac{\delta_{ij}}{3})$$

$$\tau = (1 + C'_{1\theta} \sqrt{A_2}) \frac{q^2}{\epsilon}; A_2 = a_{ij} a_{ij}$$

$$d_{ijk} = C_{3\theta} \delta_{1j} \overline{u_k \theta} + C_{4\theta} \delta_{ik} \overline{u_i \theta} + C_{5\theta} \delta_{jk} \overline{u_i \theta}$$

The model is of some complexity and involves six coefficients. A similar result was arrived at by Dakos and Gibson (1987) from the use of Fourier transforms to derive non-linear expressions by

formal solution (in wave-number space) of the Navier-Stokes and the scalar equations. In contrast to these more rigorous approachs, Craft and Launder (1989) (see also Launder, 1995) proposed that $\pi_{ij,1}$ should be modelled as:

$$\pi_{ij,1} = -C_{1\theta} \frac{\epsilon}{k} \left(\overline{u_i \theta} (1 + 0.6A_2) + C_{1\theta}^{'} a_{ik} + C_{1\theta}^{''} a_{ik} a_{kj} \right) - C_{1\theta}^{'''} R k a_{ij} \frac{\partial \Theta}{\partial x_i}$$

$$\tag{12}$$

where $C_{1\theta}$ and $C_{1\theta}^{'''}$ are functions of A_2 and the stress invariant. No explanation was offered, nor is one obvious, for the inclusion of the mean-scalar gradient in a purely turbulence-turbulence interactions term.

It will have become clear from the above that the basis for the modelling of the fluctuating pressure-scalar-gradient term are somewhat precarious. Application to wall-bounded flows introduces further uncertainties in the form of additional terms to account for the effects of a wall in damping the fluctuating pressure field in its vicinity (Gibson and Launder, 1978). These terms involve 'wall damping' functions that limit the model's applicability to simple geometries where such functions can be specified without ambiguity. All in all, therefore, it is reasonable to conclude that while gradient-transport models are inadequate, scalar-flux transport models are defective in their formulation and do not necessarily justify the increased computing overhead required. The motivation is thus clear for the abandonment of both closure strategies in favour of more rationally-derived relations of an algebraic nature.

2 Model Formulation

The proposal we wish to advance through this paper is that an explicit algebraic relation for $\overline{u_i\theta}$ may be constructed, not from the reduction of the transport equation for this quantity (as this will then involve the ill-modelled pressure-fluctuating temperature gradients term), but rather from the utilization of representation theorems based on a rationally assumed functional relationship which is then reduced through the application of appropriate constraints. For an incompressible flow with a passive scalar, the following functional relationship may be assumed:

$$-\overline{u_i\theta} = f_i(\overline{u_iu_j}, S_{ij}, W_{ij}, \Theta_{,j}, \rho, \epsilon, \overline{\theta^2}, \Theta)$$
(13)

In the presence of body forces, the relationship would become:

$$-\overline{u_t\theta} = f(\overline{u_tu_j}, S_{ij}, W_{ij}, \Theta_{,j}, \rho, \epsilon, \overline{\theta^2}, \Theta, g_t)$$
(14)

In compressible and reacting flows, the following relationship may be appropriate:

$$-\overline{u_i\theta} = f(\overline{u_iu_j}, S_{ij}, W_{ij}, \Theta_{,j}, \rho, \epsilon_{\theta}, \Theta, \overline{\theta^2}, g_i, \frac{\partial P}{\partial x_j}, \frac{\partial \rho}{\partial x_j}, M_t)$$
(15)

 M_t is the turbulent Mach number.

In the above, S_{ij} and W_{ij} are, respectively, the mean rate of strain and mean vorticity tensors:

$$S_{ij} = \frac{1}{2} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \tag{16}$$

$$W_{ij} = \frac{1}{2} \left(\frac{\partial U_i}{\partial x_j} - \frac{\partial U_j}{\partial x_i} \right) \tag{17}$$

We can introduce ϵ_{θ} which is the rate of dissipation of the scalar variance $\overline{\theta^2}$. This quantity is related to the dissipation rate of turbulence kinetic energy via the relation:

$$\frac{\epsilon_{\theta}}{\epsilon} = R^{-1} \frac{0.5\overline{\theta^2}}{0.5\overline{u_1}\overline{u_1}} \tag{18}$$

and R is the time-scale ratio which is taken as a known constant.

We confine our attention to the incompressible case for which the general representation to the functional relationship of Eq. 13 is:

$$-\overline{u_{1}\theta} = \alpha_{1}\Theta_{,1} + \alpha_{2}\tau_{ij}\Theta_{,j} + \alpha_{3}S_{ij}\Theta_{,j} + \alpha_{4}\tau_{ik}\tau_{kj}\Theta_{,j} + \alpha_{5}S_{ik}S_{kj}\Theta_{,j} + \alpha_{6}W_{ij}\Theta_{,j} + \alpha_{7}W_{ik}W_{kj}\Theta_{,j} + \alpha_{8}(S_{ik}W_{kj} + S_{jk}W_{ki})\Theta_{,j} + \alpha_{9}(\tau_{ik}S_{kj} + \tau_{jk}S_{ki})\Theta_{,j} + \alpha_{10}(\tau_{ik}W_{kj} + \tau_{jk}W_{ki})\Theta_{,j} + \alpha_{11}g_{i} + \alpha_{12}\tau_{ij}g_{j} + \alpha_{13}S_{ij}g_{j} + \alpha_{14}\tau_{ik}\tau_{kj}g_{j} + \alpha_{15}S_{ik}S_{kj}g_{j} + \alpha_{16}W_{ij}g_{j} + \alpha_{17}W_{ik}W_{kj}g_{j} + \alpha_{18}(S_{ik}W_{kj} + S_{jk}W_{ki})g_{j} + \alpha_{19}(\tau_{ik}S_{ki} + \tau_{jk}S_{ki})g_{j} + \alpha_{20}(\tau_{ik}W_{kj} + \tau_{jk}W_{ki})g_{j}$$

$$(19)$$

where

$$\alpha_i = \alpha_i(k, \epsilon, \overline{\theta^2}, \rho, I_\alpha), i = 1, ...20$$

and I_{α} consists of all possible invariants of the tensor variables listed in Eq. (13).

We may simplify the above by assuming:

- 1. the anisotropies and turbulent time scales are sufficiently small to allow for a <u>multilinear</u> expansion (the terms containing α_4 , α_5 , α_7 and α_8 are neglected):
- 2. there is equal balance between the effects of rotational and irrotational strain rates so that they enter through a production-type mechanism only. Thus we have:

$$\alpha_6 = \alpha_3$$

and

$$\alpha_{10}=-\alpha_9$$

The following compact form is then obtained:

$$-\overline{u_i\theta} = \alpha_1\Theta_{,i} + \alpha_2\tau_{i,i}\Theta_{,j} + \alpha_3U_{i,j}\Theta_{,j} + \alpha_9(\tau_{ik}U_{j,k} + \tau_{jk}U_{i,k})\Theta_{,j}$$
(20)

The lengthscale of turbulence is taken to be of the form:

$$l = \frac{k^{\frac{3}{2}}}{\epsilon} \tag{21}$$

Two different timescales are available in flows with scalar transport: the scalar timescale (τ_s) and the dynamic turbulence timescale (τ_d) . The ratio of the former to the latter is, of course, the quantity R obtained in Eq. (18). It is legitimate to use either of the two timescales for the purpose of scaling the general representation but, to be consistent with the choice of the turbulence lengthscale, we adopt the dynamic timescale which is given by:

$$\tau_d = \frac{k}{\epsilon} \tag{22}$$

With the above, the algebraic expression for $\overline{u_i\theta}$ in non-buoyant flows takes the final form to the lowest order:

$$-\overline{u_{i}\theta} = C_{1}\frac{k^{2}}{\epsilon}\frac{\partial\Theta}{\partial x_{i}} + C_{2}\frac{k}{\epsilon}\frac{\partial\Theta}{u_{i}u_{j}}\frac{\partial\Theta}{\partial x_{j}} + C_{3}\frac{k^{3}}{\epsilon^{2}}\frac{\partial U_{i}}{\partial x_{j}}\frac{\partial\Theta}{\partial x_{j}} + C_{4}\frac{k^{2}}{\epsilon^{2}}\left(\overline{u_{i}u_{k}}\frac{\partial U_{j}}{\partial x_{k}} + \overline{u_{j}u_{k}}\frac{\partial U_{i}}{\partial x_{k}}\right)\frac{\partial\Theta}{\partial x_{j}}$$

$$(23)$$

where the C's are dimensionless constants to be determined by reference to DNS and experimental data.

The first line in the simplified relation corresponds exactly to the simple gradient-transport model given in Eq. (1) when C_1 is set equal to $\frac{C_{\mu}}{\sigma_{\theta}}$. The second line is immediately recognizable as the Daly and Harlow model in Eq. (4). Lines 3 and 4 bring in dependencies that are not present in any of the algebraic models reported to date. Their presence here is supported by the outstanding analysis of Dakos and Gibson (1987) who obtained an expression for the fluctuating pressure-scalar-gradient term that contained similar products of mean velocity and scalar gradients.

It is interesting to consider at the very start some of the limiting forms of the new proposal. When a scalar gradient $\frac{\partial \Theta}{\partial y}$ is imposed on an isotropic turbulence field only the scalar-flux component $\overline{v\theta}$ is non-zero and the present relation predicts this quantity as:

$$-\overline{v\theta} = \frac{k^2}{\epsilon} (C_1 + \frac{2}{3}C_2) \frac{\partial \Theta}{\partial y}$$
 (24)

In non-isotropic turbulence, the imposition of a scalar gradient in a given direction is known to generate scalar fluxes in the directions at right angle to it. Thus, in a two-dimensional flow in the x-direction with mean-velocity U, the imposition of $\frac{\partial \Theta}{\partial y}$ would generate a scalar flux in the streamwise direction $(\overline{u\theta})$. The correct prediction of this flux component is very important in a number of situations, especially in buoyant-flow conditions (e.g. in buoyant plumes where the streamwise flux is the dominant production agency for the turbulence kinetic energy and in the classic cavity flow with one heated and one cooled vertical surfaces). Equation (1) predicts this

quantity as zero but the present proposal gives:

$$-\overline{u\theta} = C_2 \frac{k}{\epsilon} \overline{uv} \frac{\partial \Theta}{\partial y}.$$
 (25)

In a flow with finite $\frac{\partial \Theta}{\partial y}$, the imposition of a velocity gradient in the same direction may increase or decrease the streamwise scalar flux depending on whether the sign of the velocity gradient is the same or opposite that of the scalar gradient. For this case, the present proposal gives:

$$-\overline{u}\overline{\theta} = C_2 \frac{k}{\epsilon} \overline{u} \overline{v} \frac{\partial \Theta}{\partial y} + C_3 \frac{k^3}{\epsilon^2} \frac{\partial U}{\partial y} \frac{\partial \Theta}{\partial y} + C_4 \frac{k^2}{\epsilon^2} \overline{v}^2 \frac{\partial U}{\partial y} \frac{\partial \Theta}{\partial y}$$

$$(26)$$

We consider below the relation between the model proposed herein and a number of existing alternatives. Yoshizawa (1985) used the two-scale direct interaction approximation to obtain a diffusion tensor (D_{ij}) which is linear in the velocity gradients. His result, which is valid for arbitrary Reynolds numbers, is given by:

$$D_{ij} = C_1 \frac{k^2}{\epsilon} \delta_{ij} - C_2 \frac{k^3}{\epsilon^2} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right)$$
 (27)

In a shear flow with finite $\frac{\partial U_1}{\partial x_2}$, this formulation does not permit for the diffusivity components D_{12} and D_{21} to be unequal. This latter defect was absent from the formulation of Rubinstein and Barton (1991), obtained by application of renormalization group theory. At high Reynolds number, their model gives:

$$D_{ij} = C_1 \frac{k^2}{\epsilon} \delta_{ij} - C_2 \frac{k^3}{\epsilon^2} \frac{\partial U_j}{\partial x_i} - C_3 \frac{k^3}{\epsilon^2} \frac{\partial U_i}{\partial x_i}$$
 (28)

Yoshizawa (1988) made a further proposal, given by:

$$D_{ij} = 4C_k \left(\frac{\overline{\theta^2}}{\epsilon_b}\right)^2 \epsilon \delta_{ij} - 8\left(\frac{\overline{\theta^2}}{\epsilon_\theta}\right)^3 \epsilon \left[C_1 \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i}\right) + C_1' \left(\frac{\partial U_i}{\partial x_j} - \frac{\partial U_j}{\partial x_i}\right)\right]$$
(29)

None of these models contain an explicit dependence on $\overline{u_iu_j}$, something which is clearly present in the exact equation for $\overline{u_i\theta}$. This dependence was restored in the model of Rogers et al. (1989) who replaced the terms representing the time-change of the scalar fluxes, their dissipation and the fluctuating pressure-scalar-gradient correlations by a multiple of the scalar-flux vector. Their model is given by:

$$\overline{u_1\theta} = -O_{in}^{-1} \overline{u_n u_j} \frac{\partial \Theta}{\partial x_i} \tag{30}$$

where O^{-1} is the reciprocal of the determinant of the tensor O_{ij} which is defined as:

$$O_{ij} = \frac{C_D}{\tau} \delta_{ij} + \frac{\partial U_i}{\partial x_i} \tag{31}$$

where τ is the timescale.

The authors point out that the matrix O_{ij} becomes stiff for values of $S\tau/C_D >> 1$ but the model suffers a more serious problem; namely, for flows subjected to normal mean strains—such as plane strain or the axisymmetric expansion/contraction – Eq. (30) is not necessarily invertible rendering Eq. (29) singular (see Appendix).

The relationship between the present model and the alternatives can best be seen from Tables 1-4 where various components of the diffusivity tensor (D_{ij}) obtained with those models are presented. The results are for the case where $\frac{\partial U}{\partial y}$ is the only non-zero velocity gradient.

3 Appendix

We consider the performance of the Rogers et al. (1989) model with respect to the case of mean flow plane strain i.e. where:

$$U_{1,1} = -U_{2,2} = S$$

and all other components of $U_{i,j}$ are zero. For this case:

$$\underline{Q} = \begin{bmatrix}
\frac{C_D}{\tau} + S & 0 & 0 \\
0 & \frac{C_D}{\tau} - S & 0 \\
0 & 0 & \frac{C_D}{\tau}
\end{bmatrix}$$
(A1)

and, obviously,

$$\underline{Q}^{-1} = \begin{bmatrix} \frac{\tau}{C_D + S\tau} & 0 & 0\\ 0 & \frac{\tau}{C_D - S\tau} & 0\\ 0 & 0 & \frac{\tau}{C_D} \end{bmatrix}$$
(A2)

So, for arbitrary turbulence

$$\overline{u_1\theta} = \left(\frac{\tau}{C_D + S\tau}\right) \left(\overline{u_1u_1}\frac{\partial\Theta}{\partial x_1} + \overline{u_1u_2}\frac{\partial\Theta}{\partial x_2} + \overline{u_1x_3}\frac{\partial\Theta}{\partial x_3}\right) \tag{A3}$$

$$\overline{u_2\theta} = (\frac{\tau}{C_D - S\tau}) \left(\overline{u_2u_1} \frac{\partial \Theta}{\partial x_1} + \overline{u_2u_2} \frac{\partial \Theta}{\partial x_2} + \overline{u_2u_3} \frac{\partial \Theta}{\partial x_3} \right) \tag{A4}$$

$$\overline{u_3\theta} = \left(\frac{\tau}{C_D}\right) \left(\overline{u_3u_1}\frac{\partial\Theta}{\partial x_1} + \overline{u_3u_2}\frac{\partial\Theta}{\partial x_2} + \overline{u_3u_3}\frac{\partial\Theta}{\partial x_3}\right) \tag{A5}$$

Clearly, if $C_D = S\tau$, the scalar-flux $\overline{u_2\theta}$ becomes infinite. In the vicinity of $C_D \approx S\tau$, the result will be unphysical. For any general irrotational mean flow strain, this model would suffer from similar defects.

Table 1. Models results for diffusivity-tensor component D_{11}

Table 2. Models results for diffusivity-tensor component D_{22}

Model		
Present	$C_1 \frac{k^2}{\zeta}$ $C_1 \frac{k^2}{\zeta}$	$+C_2\frac{k}{\epsilon}\overline{v^2}$
Yoshizawa (1985)		
Yoshizawa (1988)	$4C_k \left(\frac{\overline{\theta^2}}{\epsilon_{\mu}}\right)^2 \epsilon$	
Rogers et al. (1989)	, .	$\frac{1}{C_D} \frac{k}{\epsilon} \overline{v^2}$
Rubinstein and Barton (1991)	$C_i \frac{k^2}{\epsilon}$	

Table 3. Models results for diffusivity-tensor component D_{12}

Model	,	3 21:	- 12 - a):
Present	$C_2 \frac{\kappa}{\epsilon} \overline{u} \overline{v}$	$+C_3 \frac{k^3}{\epsilon^2} \frac{\partial U}{\partial y} \\ -C \frac{k^3}{\epsilon^2} \frac{\partial U}{\partial y}$	$+C_4\frac{k^2}{\epsilon^2}\overline{v^2}\frac{\partial U}{\partial y}$
Yoshizawa (1985)			
Yoshizawa (1988)		$-8\left(\frac{\overline{\theta^2}}{\epsilon_{\theta}}\right)^3 \epsilon (C_1 + C_1') \frac{\partial U}{\partial y}$	_
Rogers et al. (1989)	$\frac{1}{C_D} \frac{k}{\epsilon} \overline{uv}$		$-\frac{1}{C_D^2}\frac{k^2}{\epsilon^2}\overline{v^2}\frac{\partial U}{\partial y}$
Rubinstein and Barton (1991)		$076 \frac{k^3}{\epsilon^2} \frac{\partial U}{\partial y}$	_

Table 4. Models results for diffusivity-tensor component D_{21}

Model		_
Present	$C_2 \frac{k}{\epsilon} \overline{u} \overline{v}$	$+C_4 \frac{k^2}{\epsilon^2} \overline{v^2} \frac{\partial U}{\partial y}$
Yoshizawa (1985)		$+C_4 \frac{k^2}{\ell^2} \overline{v^2} \frac{\partial U}{\partial y} \\ -C \frac{k^3}{\ell^2} \frac{\partial U}{\partial y}$
Yoshizawa (1988)		$-8\left(\frac{\overline{\theta^2}}{\epsilon_{\theta}}\right)^3 \epsilon (C_1 - C_1') \frac{\partial U}{\partial y}$
Rogers et al. (1989)	$\frac{1}{CD}\frac{k}{\epsilon}\overline{uv}$, , ,
Rubinstein and Barton (1991)	-	$-0.166 \frac{k^3}{\epsilon^2} \frac{\partial U}{\partial y}$

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